## SWALE OCEANOGRAPHIC

## Receivers for Pingers \& Transponders.

## STI-350 - Surface Receiver

The STI-350 is a small battery operated directional receiver that's designed to track both underwater pingers and transponders from the surface. An LCD display provides navigation data to the operator while sealed switches allow easy access to control functions of the deck box.

When operating in passive mode, the STI-350 can locate standard acoustic beacons that operate from 25 to 45 kHz . The STI-350 displays signal strength and bearing to the selected acoustic beacon. A built-in electronic compass provides additional directional support in keeping the operator on course.


The STI-350 can also track and locate transponders designed to work with the receiver. These transponders allow divers to mark targets underwater and re-locate them up to 750 metres away. The STI- 350 provides accurate range and bearing to the transponder to within 1m.

The STI-350 includes Surface Transponder Interrogator, Battery Charger, Pole Assembly, Directional Hydrophone, Cable Assembly, and Operations Manual.

## DPR-275 Diver Receiver for pinger

The DPR-275 is extremely rugged, reliable, and intended for use in a hostile marine environment. RJE's extensive back- ground allowed it to design a diver pinger receiver that will provide years of operation with a minimal amount of maintenance. Using digital signal processing, the DPR-275 can track and locate any underwater acoustic beacons operating between 5 to 80 kHz . Rechargeable batteries provide up to eight hours of continuous use.

A highly sensitive directional hydrophone allows the diver to hone-in on a beacon's acoustic signal from up to 1,200 metres away ( $37 \mathrm{kHz} / 162.5 \mathrm{~dB}$ source). Large control knobs allow the operator to
 access the DPR-275's functions, even with thick gloves. When the DPR-275 is pointed in the direction of an acoustic beacon, the unit generates an audio tone through an underwater headset providing the necessary feedback for relocation. To back up the audio tone, a signal strength meter provides additional feedback to the location of the beacon.
The DPR-275 includes an underwater headset, battery charger, and storage case.

## DTI-300A Diver Receiver for pingers \& transponders

The DTI-300A is a small battery operated acoustic receiver that can track and locate underwater acoustic beacons and a unique family of acoustic transponders. It is ergonomically designed to be operated by a diver and uses a LCD display to provide navigation data. Sealed switches allow the diver access to the control and utility functions of the receiver.

When operating in the passive mode, the DTI-300A can locate standard acoustic beacons which operate from 25 to 45 kHz . The DTI-300A display provides the operator signal strength and bearing to the selected acoustic beacon. A built-in electronic compass provides additional directional support to keep the diver on course.


The DTI-300A can also track and locate transponders designed to work with the receiver. The ATT-400 transponder allows divers to mark targets underwater and relocate them up to 750 metres away. Once an ATT-400 has been interrogated, the DTI-300A provides accurate range and bearing to the transponder to within 1 metre. Because the ATT-400 can be programmed to operate on eight (8) different channels, the DTI-300A can relocate eight different locations simultaneously.

## VADR - Vehicle Acoustic Directional Receiver

The VADR acoustic directional receiver is a small but rugged passive pinger receiver used to assist operators of ROVs and AUVs in tracking acoustic sound sources from 8 kHz to 45 kHz . In addition, they can function as an acoustic transponder interrogator and provide accurate range and bearing to targets marked with a line of custom acoustic transponders.

The VADR receiver's small size and rugged design allows for easy mounting on a ROV or AUV. Electronics and a highly directional hydrophone are contained in the pressure
 housing and are externally powered by the subsea vehicle through a 5 -pin bulkhead connector. In addition, all telemetry data for controlling the VADR receivers and output data is accessed through this same connector.

A RS232 data interface is used to access the directional indication, range to target, and other operational information and control functions of the VADR receivers using an ASCII data string. Software is also provided to allow the operator easy access to control and receive the necessary directional information to track the acoustic sound source.

For tracking an acoustic sound source, like a "Black Box" beacon, the operator selects the proper frequency through the SEEKER software. The VADR receiver begins to look for that acoustic signal through a directional hydrophone which is mounted into the front of the pressure housing. Once received, the signal is processed by the electronics and fed to the software. Then bearing data and signal strength is provided to the ROV operator for navigating the ROV to the target area. In addition, the ROV operator can also change the mode of the VADR receiver to track and locate acoustic transponders. This option allows the ROV operator to mark locations or equipment underwater with accuracies within one metre. Because the system is now operating as a transponder interrogator, the feedback to the ROV operator is more accurate as range and bearing data is delivered to the SEEKER software. Each transponder can be programed to reply on eight different frequencies allowing the marking of multiple locations within an operational range of up to 750 m .

## Specifications

|  | STI-350 | DTI-300A | DPR-275 | VADR-6000m |
| :---: | :---: | :---: | :---: | :---: |
| Passive Mode |  |  |  |  |
| Receiver Bandwidth | 25 to 45 kHz ( 1 kHz steps) | 25 to 45 kHz (1kHz steps) | 5 to 80 kHz (1kHz steps) | 8 to 45kHz (100Hz steps) |
| Receiver Sensitivity |  |  |  | -100dB ref $1 \mu \mathrm{~Pa}$ @ 1 metre |
| Active Mode |  |  |  |  |
| Transmit Frequency | 26 kHz | 26 kHz |  | 26 kHz |
| Receive Frequency | 27,28,29,30,31,32,33,34 kHz | 27,28,29,30,31,32,33,34 kHz |  | $\begin{aligned} & \text { 25, 27,28,29,30,31,32,33,34 } \\ & \text { kHz } \end{aligned}$ |
| Acoustic Output | 180db (coded) | 190db (coded) |  | 190db (coded) |
| System Range | 750m | 750m |  | 750m |
| Compass | Electronic | Electronic | Analogue |  |
| Accuracy | $<0.5^{\circ}$ to $1.5^{\circ} \mathrm{RMS}$ | $<0.5^{\circ}$ to $1.5^{\circ} \mathrm{RMS}$ |  |  |
| Repeatability | $\pm 0.3^{\circ}$ | $\pm 0.3^{\circ}$ |  |  |
| Transducer/Hydrophone | Directional |  | Directional ( $30^{\circ}$ ) | Directional (see below) |
| Display | LCD | LCD | LCD \& LED | PC via RS-232 and software |
| Information | Range or Signal Strength, Compass Bearing, Bearing Indicator to Target, Channel Indicator, Low Battery,. | Range or Signal Strength, Compass Bearing, Bearing Indicator to Target, Channel Indicator, Low Battery | Frequency, Signal Strength Meter, Low Battery |  |
| Control Switches | Sealed Switches | Sealed Piezo-ceramic |  |  |
| Battery | Rechargeable | Rechargeable | Rechargeable |  |
| Operational Life | 8 hours | 6 hours | 8 hours |  |
| Depth Rating | n/a | 100m | 200m | 6000m |
| Housing | Waterproof to IPX4 | Delrin | Delrin | Anodized Aluminium |
| Size (LxWxH) | $28 \times 25 \times 13 \mathrm{~cm}$ | $33 \times 18 \times 7 \mathrm{~cm}$ | Ø10.4 x L26.0cm | $\varnothing 12.7 \times$ L28.0cm |
| Weight (air / water): | 2.9 kg | $5 \mathrm{~kg} /-0.19 \mathrm{~kg}$ | $2.0 \mathrm{~kg} / 0.19 \mathrm{~kg}$ | $6.8 \mathrm{~kg} / 5.5 \mathrm{~g}$ |
| Other: | Inc 3m pole assy \& cable | For use with ATT-400 transponders | Cable \& pole assy option (PRS-275) | Beam: $40 \pm 5^{\circ}$ conical. <br> Bearing: 4 BINS: Left / right, $3,8,20 \text { or }>20^{\circ}$ <br> Accuracy $5^{\circ}$ (bins 1 \& 2) Resolution $2^{\circ}$ |

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